

# Introduction to Structural Analysis

Mark A. Austin

University of Maryland

*austin@umd.edu*

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  - Connecting Analysis to Structural Design
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# Introduction

# Definition of Structural Mechanics

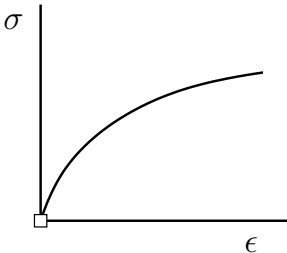
**Mechanics.** Branch of [science](#) that deals with [response of matter](#) to [forces](#).

Civil Engineering:

- Structural mechanics ( $\sigma - \epsilon$ ): material displacement.
- Geomechanics ( $\sigma - \epsilon$ ): pressure, temperature, displacements.
- Fluid mechanics ( $\sigma - \epsilon$ ): pressure, velocities.

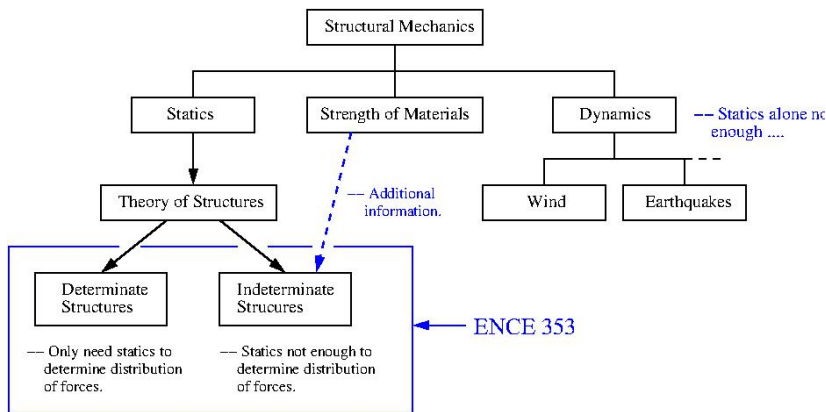
Other domains:

- Biomechanics ( $\sigma - \epsilon$ ): eye, heart, biological systems that grow!



# Structural Mechanics and Analysis

Structural Mechanics → Static / Dynamic Analysis of Structures:



# Structural Mechanics and Analysis

Scope of this class:

- We will be concerned with **structural systems** that are **attached to the ground**.

Pathway forward:

- Connect mechanics to analysis ...
- Connect analysis to design ...
- Theory of structural analysis ...

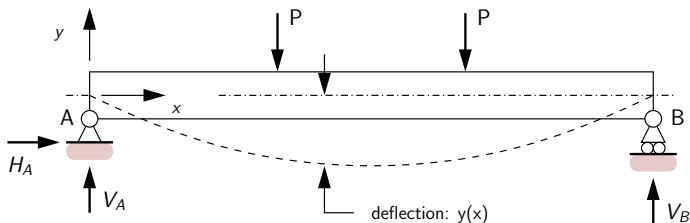
Statically **determinate** structures ...

Statically **indeterminate** structures ...

- Simplifying assumptions ...

# Connecting Mechanics to Analysis

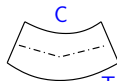
# Structural Mechanics and Analysis



## Internal Forces

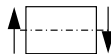
Bending Moment

$M(x)$



Shear Force

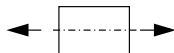
$V(x)$



Elongation

Axial Force

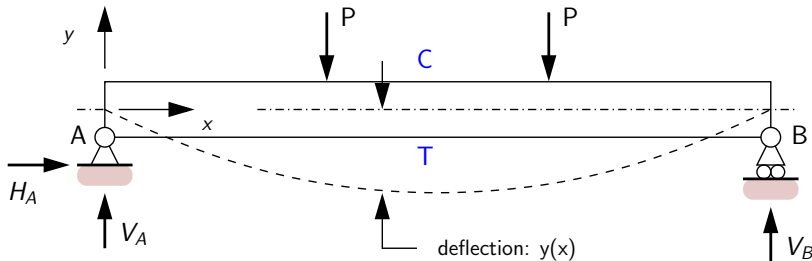
$N(x)$





# Concrete Beam: Load-to-Failure Experiment

## Experimental Setup

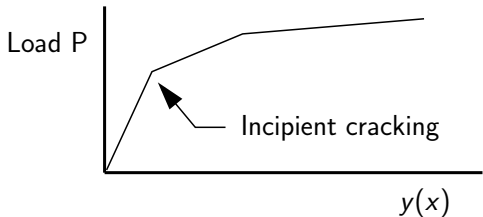


## Bending Moment Diagram (BMD)



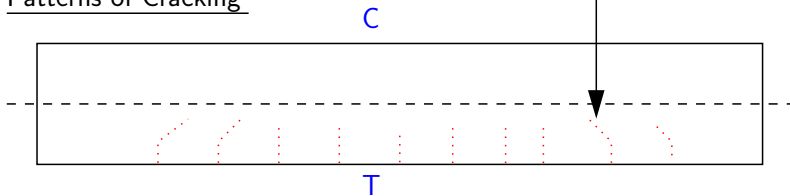
# Concrete Beam: Load-to-Failure Experiment

## Applied Load $P$ versus Midspan Deflection



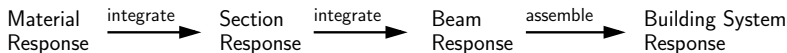
Direction of cracking perpendicular to slope of BMD.

## Patterns of Cracking



# Pathway from Mechanics to System-Level Behavior

From material-level mechanics to building-system response:



Stress

$$\sigma(x, y)$$

Strain

$$\epsilon(x, y)$$

Curvature

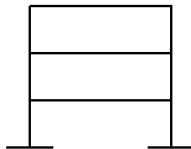
$$\phi(x) = \left[ \frac{M(x)}{EI} \right]$$

Deflection

$$y(x)$$

Slope

$$dy/dx$$



How will the integration work?

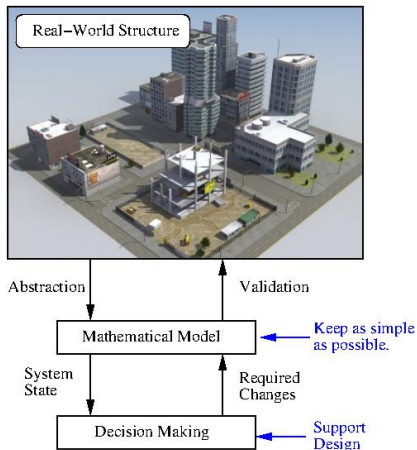
- Analytical Procedures: The **math needs to be "nice"** ...
- Numerical Procedures: Compute approximate solutions  $\rightarrow$  linear algebra, numerical algorithms, structural analysis and finite elements.

# Connecting Analysis to Design

# Framework for Analysis and Design

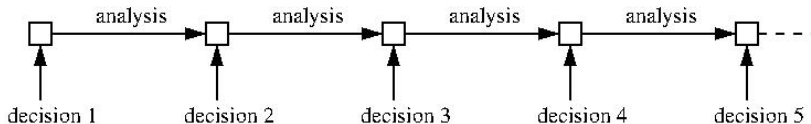
## Creating an Analysis Model

- **Abstract** from consideration details not needed for decision making.
- **Validate** that model captures essential aspects of real-world behavior.
- **Decision making** needed for design.
- **Perfect is the enemy of good.** Mathematical model and decision making does not need to be perfect in order to be useful.



# Connecting Analysis to Design

**Structural Design.** Sequence of analyses punctuated by decision making.



add detail

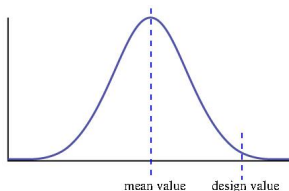
less abstract

- Determine types and magnitudes of loads and forces acting on the structure.
- Determine context of project: geometric constraints, architectural constraints, geological conditions, urban regulations, cost, schedule, etc.

# Connecting Analysis to Design

- Generate **structural system alternatives**.
- **Analyze** one or more of the **alternatives**.
- Select and perform detailed design.
- Implement/build.

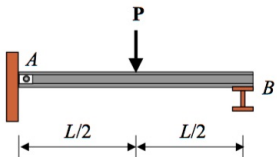
Analysis and decision making procedures complicated by uncertainties in loading, material properties, etc. State-of-the-art methods **compensate for uncertainties** with **safety factors**.



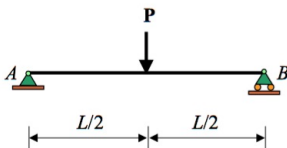
New structural systems may also require an **experimental testing** phase to **verify behavior** and **achievable system performance**.

# Connecting Analysis to Design

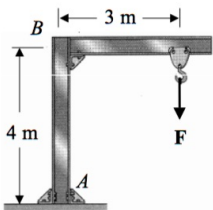
## Real-World and Idealized Abstractions



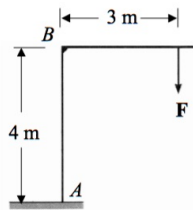
actual beam



idealized beam



actual structure



idealized structure

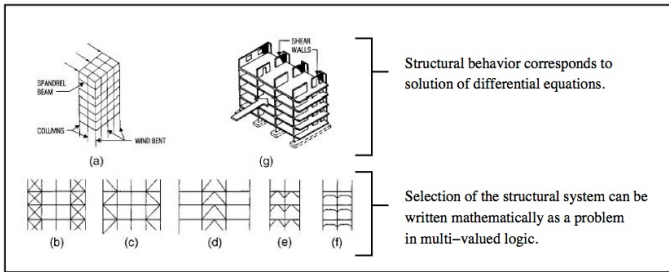


# Connecting Analysis to Design

## Formal Approaches to Behavior Modeling and Decision Making

Appropriate formalisms depend on the design domain of interest.

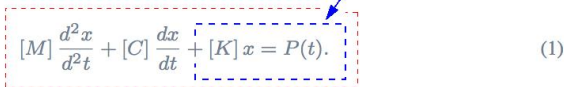
- Physical aspects of behavior are often characterized by differential equations.
- Logical aspects of system design can be captured by binary and multi-valued logic variables and boolean equations.



# Connecting Analysis to Design

## Structural Behavior

Time-dependent behavior corresponds to solutions of:

$$[M] \frac{d^2x}{dt^2} + [C] \frac{dx}{dt} + [K]x = P(t). \quad (1)$$


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Here,

- M, C, and K are  $(n \times n)$  matrices,
- x is a  $(n \times 1)$  vector of displacements,
- P(t) is a vector of external loads applied to the structural degrees of freedom.

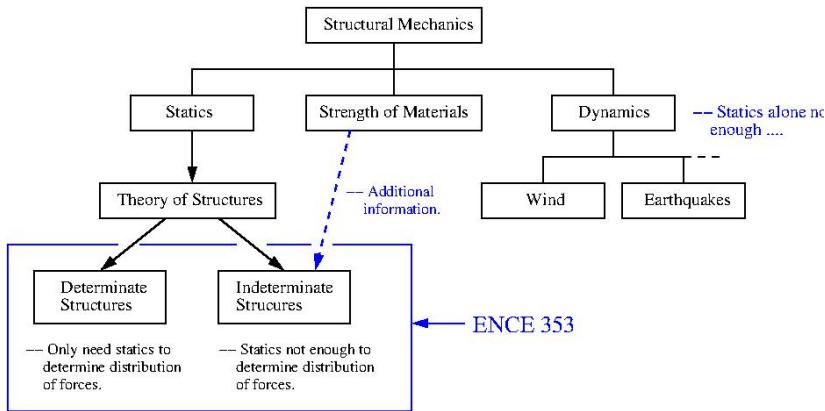
## Design Parameters

- Selection of the best structural system (e.g., braced system) from a list of options.
- Size of the beams, columns, and bracing (if required).

# Theory of Structures

# Theory of Structures

Structural Mechanics → Static / Dynamic Analysis of Structures:



# Statically Determinate Structures

**Definition.** Can **use statics** to **determine reactions** and distribution of element-level forces. Determinacy is **not affected** by **details of loading**.

## Two-Dimensional Problems

$$\sum F_x = 0, \quad \sum F_y = 0, \quad \sum M_z = 0. \quad (1)$$

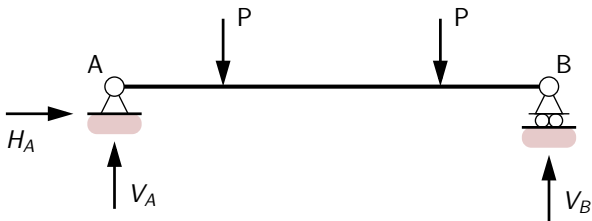
## Three-Dimensional Problems

$$\sum F_x = 0, \quad \sum F_y = 0, \quad \sum F_z = 0. \quad (2)$$

$$\sum M_x = 0, \quad \sum M_y = 0, \quad \sum M_z = 0. \quad (3)$$

# Statically Determinate Structures

**Example 1.** Simply supported beam:

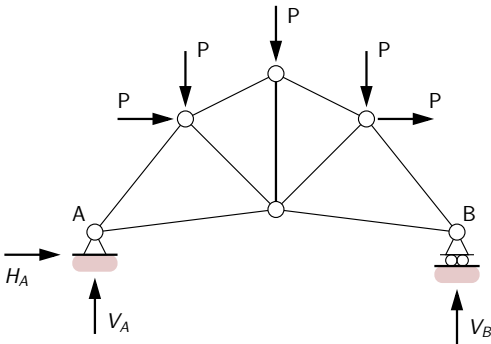


Three equations of equilibrium:  $\sum F_x = 0$ ,  $\sum F_y = 0$ ,  $\sum M_z = 0$ .

Three unknowns:  $V_A$ ,  $H_A$  and  $V_B \rightarrow$  Can use statics to solve.

# Statically Determinate Structures

**Example 2.** Small truss structure:

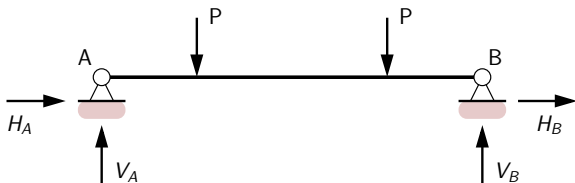


- Use statics to find support reactions  $V_A$ ,  $H_A$  and  $V_B$ .
- Compute member forces by considering equilibrium of individual joints.

# Statically Indeterminate Structures

**Definition.** Statics alone are **not enough** to **find reactions**. Need to find additional information (e.g., material behavior).

**Example 1.** Simply supported beam:



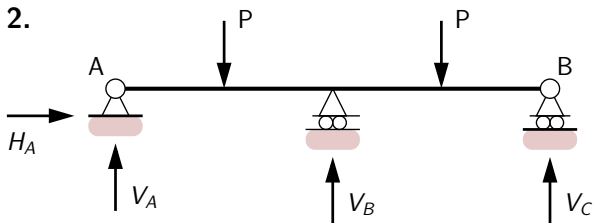
Three equations of equilibrium:  $\sum F_x = 0$ ,  $\sum F_y = 0$ ,  $\sum M_z = 0$ .

Four unknowns:  $V_A$ ,  $H_A$ ,  $V_B$  and  $H_B \rightarrow 4 > 3 \rightarrow$  **statically indeterminate** to **degree 1**.



# Statically Indeterminate Structures

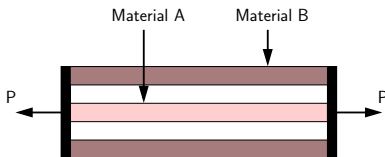
## Example 2.



Three equations of equilibrium. Four unknowns:  $V_A$ ,  $H_A$ ,  $V_B$  and  $V_C \rightarrow 4 > 3 \rightarrow$  **statically indeterminate to degree 1.**

## Example 3. Multi-material Truss Element.

Material behavior defined by  $\sigma - \epsilon$  characteristics.  
Need to maintain geometric compatibility.



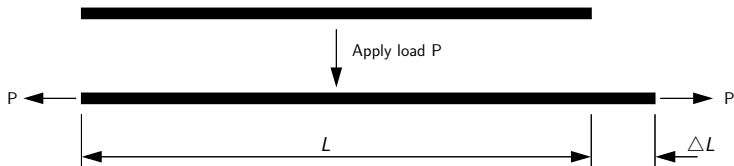
# Simplifying Assumptions for ENCE 353

Small Displacements  
Linear Systems Behavior

# Assumption 1: Small Displacements

**Definition.** We assume that application of loads will cause a displacement (i.e., elements are not rigid).

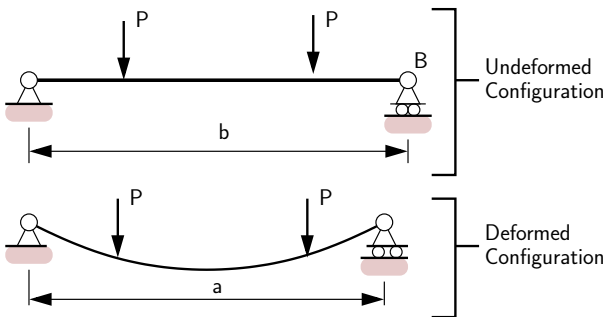
**Example 1.** Axial extension of a Rod



Small displacements means  $\Delta L \ll L$ , i.e.,  $\left[ \frac{\Delta L}{L} \right] \ll 1$ .

# Assumption 1: Small Displacements

## Example 2. Flexure of Beam Elements.



For steel/concrete structures:  $a \approx b$  (i.e.,  $a > 0.99b$ )  $\rightarrow$  compute equilibrium with respect to the undeformed configuration.

# Assumption 1: Counter Examples

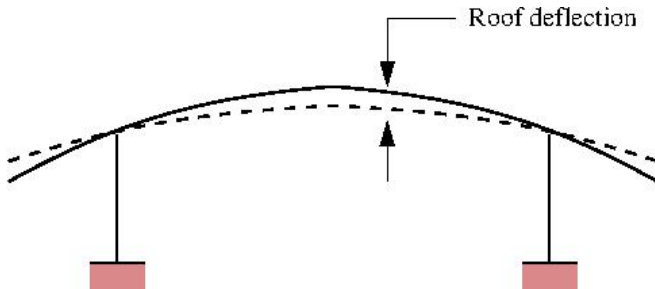
**Arch Structures.** Vintage Safeway Supermarkets.



**Style:** Use mid-century modern arch shape to create large open spaces.

# Assumption 1: Counter Examples

**Nice Trick:** When heavy snow loads cause large roof deflections, arch mechanism gives illusion of safety!

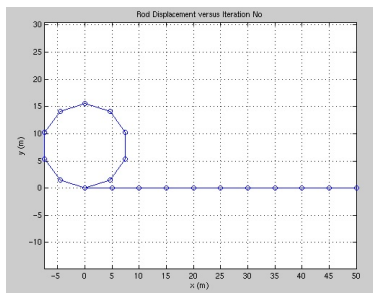


**Google:** safeway roof collapse.

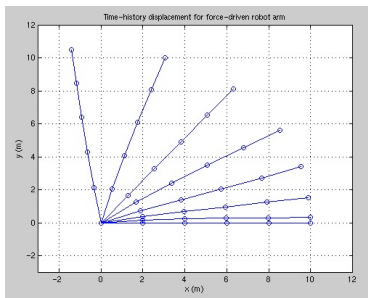
# Assumption 1: Counter Examples

**Large Geometric Displacements.** Wind turbine blades, flexible robot arms, etc ...

Roll cantilever into circle.



Flexible robot arm maneuver.

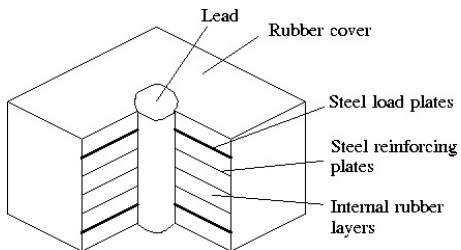


Source: Simo, Vu-Quoc, 1986.

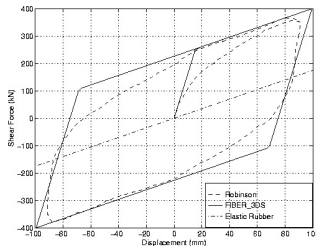
# Assumption 1: Counter Examples

**Large Material Displacements.** Behavior of Lead-Rubber Isolators under Large Cyclic Earthquake Loads.

## Lead-Rubber Laminated Bearing



## Hysteresis Loops



Source: Lin W-J., 1997.



## Assumption 2: Linear Systems Behavior

**Mathematical Definition.** Let  $k$  be a non-zero constant. A function  $y = f(x)$  is said to be linear if it satisfies two properties:

- $y = f(kx_1)$  is equal to  $y = kf(x_1)$ .
- $f(x_1 + x_2) = f(x_1) + f(x_2)$ .

For constants  $k$  and  $m$  these equations can be combined:

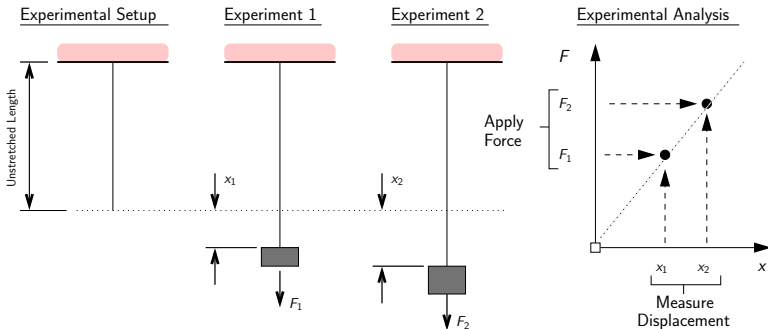
$$kf(x_1) + mf(x_2) \rightarrow f(kx_1 + mx_2). \quad (4)$$

**Economic Benefit.** Often **evaluation** of  $y = f(x)$  has a **cost**.

Linearity allows us to compute  $y_1 = f(x_1)$  and  $y_2 = f(x_2)$  and then predict the system response for  $kx_1 + mx_2$  via linear combination of solutions. This is free!

# Assumption 2: Linear Systems Behavior

**Example 1.** Consider an experiment to determine the extension of an elastic chord as a function of applied force.



Linearity allows us to predict solutions:

$$Kx_1 = F_1, Kx_2 = F_2, \rightarrow K(mx_1 + nx_2) = mF_1 + nF_2. \quad (5)$$

## Assumption 2: Linear Systems Behavior

### Example 2. Analysis of Linear Structural Systems:

Suppose that matrix equations  $AX = B$  represent behavior of a structural system:

- Matrix A will capture the geometry, material properties, etc.
- Matrix B represents externally applied loads (e.g., dead/live gravity loads).
- Column vector X represents nodal displacements.

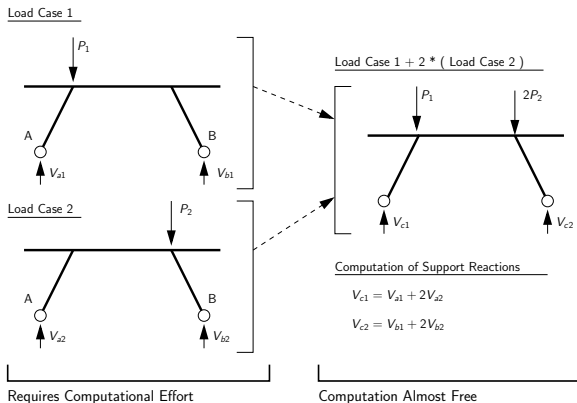
Solving  $AX = B$  has computational cost  $O(n^3)$ .

However, if matrix system is linear, then:

$$AX_1 = B_1, AX_2 = B_2 \rightarrow A(mX_1 + kX_2) = mB_1 + kB_2. \quad (6)$$

# Assumption 2: Linear Systems Behavior

We can simply **add the results** of **multiple load cases**:



Works for support reactions, bending moments, displacements, etc.

# Symmetries

# Taking Advantage of Symmetry

**Observation.** Symmetries provide engineers with an opportunity to reduce **model size** and **computational effort**.

**Definitions.** Here's what a mathematician would say:

- A function is even (**symmetric**) when  $y = f(x) = f(-x)$ .  
Examples:  $y = x^2$  and  $y = \cos(x)$ .
- A function is odd (**skew-symmetric**) when  $y = g(x) = -g(-x)$ .  
Examples:  $y = x^3$  and  $y = \sin(x)$ .

**Home Exercise.** Show that:

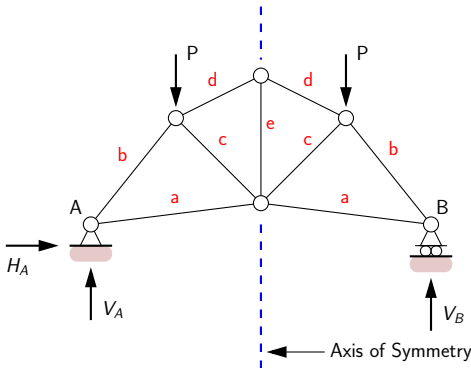
$$\int_{-a}^a f(x)g(x)dx = 0. \quad (7)$$

We will use this later in the course to simplify analysis.

# Taking Advantage of Symmetry

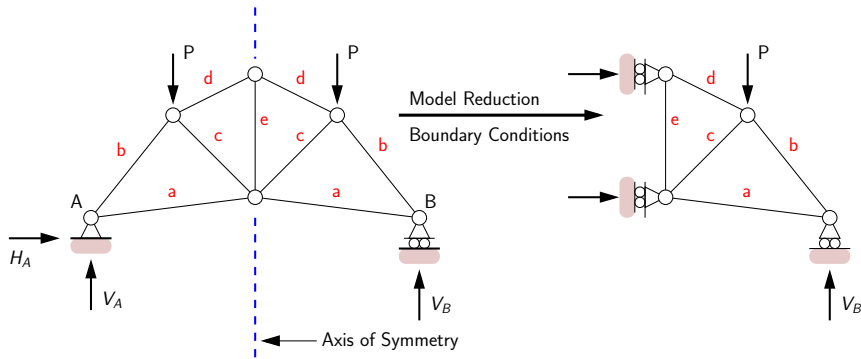
**Example 1.** Consider the Small Truss Structure:

- Axis of symmetry works for geometry, loading patterns and reactions.
- Only need to compute member forces  $a - e$ .
- Model reduction requires careful treatment of boundary conditions.



# Taking Advantage of Symmetry

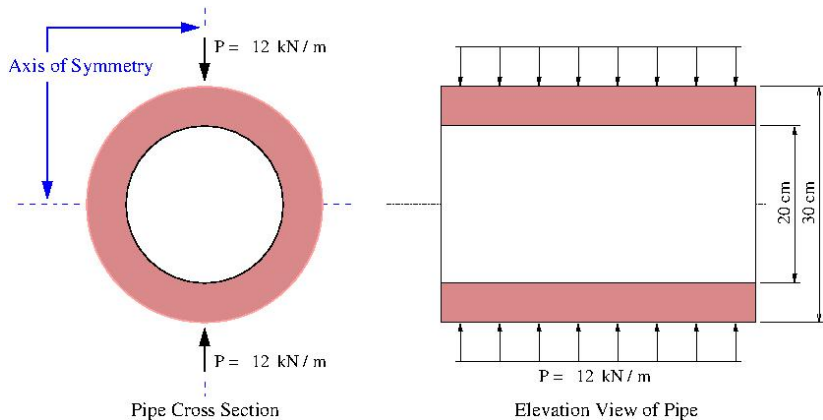
**Model Reduction:** Cut model size in half, then adjust boundary conditions along axis of symmetry.





# Taking Advantage of Symmetry

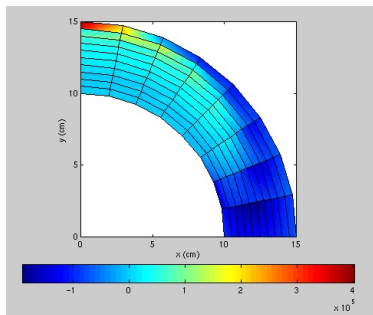
## Example 2. Stress Analysis in Cross Section of a Long Pipe



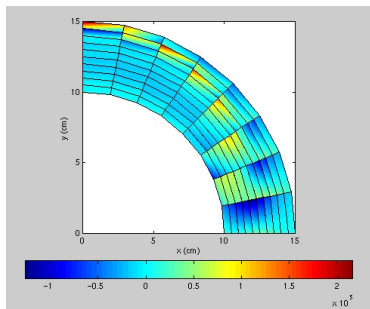
# Taking Advantage of Symmetry

Two axes of symmetry for geometry and loading → Only need to analyze 1/4 of the cross section.

Stresses:  $\sigma_{yy}(x, y)$



Stresses:  $\sigma_{xx}(x, y)$



## References

- Wane-Jang Lin, Modern Computational Environments for Seismic Analysis of Highway Bridge Structures, PhD Thesis, University of Maryland, College Park, MD, 1997.
- Simo J.C., Vu-Quoc L., On the Dynamics of Flexible Beams Under Large Overall Motions—The Plane Case: Part II, Journal of Applied Mechanics, (53) 4, 855-863, 1986.